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## **AC Inverter Drives**







## The New Generation of AC Drives



Larsen & Toubro's New Generation AC Drives incorporate the latest technological advancements in AC induction motor speed control.

### Performance and Technology

L&T offers a range of performance choices and innovative technologies. Control methods include V/f, open loop vector and closed loop vector control for speed regulation choices.

### Standards & Reliability

•MTBF: Exceeds 28 years •Tested on fully-loaded motors Surface mount technology •Protective PCB coating •0.6G or less (20 to 55Hz) •UL, cUL and CE listed

### Easy To Use

The New Generation Drives are factory-programmed and ready to run. J7, V7, V1000 & F7 drives have standard LED display. The keypad is intuitive and includes parameter-copying functions to copy parameters from one drive to another.

### **Commissioning Software: Drive Wizard**

This support tool is a windows based PC program designed to make commissioning and troubleshooting of these drives as simple as possible. The user friendly Drive Wizard exchanges data with drive and data can be retrieved, reviewed, changed, stored and graphed.

J7, V7, V1000 & F7 AC Drives are manufactured by : **YASAKAWA Electric Corporation** JAPAN

# Salient Features of J7, V7, F7 & V1000 Drives

### **Performance Features**

- Adjustable S-curves for acceleration and deceleration
- DC injection braking: at start or stop
- Power loss ride-through for protection against momentary power loss/under voltage
- Volts/Frequency ratio: fully adjustable
- ➡ Drive efficiency: 96 to 98%
- Displacement power factor: 0.98
- Output frequency: 1.0 to 400 Hz
- Torque boost: full range
- Critical frequency rejection settings
- Carrier frequency is selectable



- Heat sink over-heat to give overload protection to inverter
- Current-limiting DC bus fuse to protect inverter

- Short circuit withstanding rating: 65kA RMS
- protection
  - Optically-isolated controls: to completely isolate control circuit from power circuit

### **Protective Features**

### Torque limit

- Motor overload protection
- Phase-to-phase, ground fault and short circuit protection
- Over/under torque protection
- Input/output single phasing

### **User Friendly Features**

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- Digital keypad operator
- Copy keypad function
- ➡ 24 VDC control logic for sourcing sourcing outputs (both PNP or NPN transistors)
- ➡ RJ-45 style digital operator connector
- Multi speed settings plus jog speed
- ➡ Flash RAM software memory for update
- Split front cover for easy wiring
- Heat sink fan: Plug-in with on-off control



# Micro Size OEM Drive



The J7 drive is a general purpose AC drive; its sine wave PWM design provides low motor noise and high starting torque, with a current overload rating of 150% for 60 seconds. The J7 is feature-packed, compact yet economical and its V/f control makes the drive suitable for most of the general applications. The digital operator includes a 3-digit LED status display. An optional RS-485 Modbus RTU serial communication port is available. An ideal choice whenever economy and compactness are required.

### Common Applications

- Conveyors
- Grinders
- Centrifuges
- PumpsFans
- Blowers
- Mixers
- Commercial Laundry
- Automotive Assembly
- Packaging Equipment
- Material Handling

### Features

- Full range automatic torque boost function can deliver outstanding starting torque
- High speed current limiting function for tripless operation
- Slip compensation function for excellent speed regulation
- Speed search function for automatic restart after power loss
- Compact space saving design with uniform height of 128mm on all models

### STANDARD SPECIFICATIONS

VOLTAGE CLASS		200 V s	ingle-pha	se			40	00 V three	-phase			
MODEL CIMR-J7AA	B0P20	B0P40	B0P70	B1P50	40P20	40P40	40P70	41P50	42P20	43P00	43P70	
/lax. Applicable kW	0.2	0.4	0.75	1.5	0.2	0.4	0.75	1.5	2.2	3	3.7	
notor output * HP	0.25	0.5	1	2	0.25	0.5	1	2	3	4	5	
Inverter rated kVA	0.6	1.1	1.9	3	0.9	1.4	2.6	3.7	4.2	5.5	7	
Rated output current (A)	1.6	3	5	8	1.2	1.8	3.4	4.8	5.5	7.2	8.6	
Max. Output voltage (V)	(p	200 to 240 V (proportional to input voltage) 380 to 460 V (proportional to input voltage)										
Rated output current (A) Max. Output voltage (V) Max. Output frequency (Hz)						400 Hz						
Rated input voltage and frequency	1-pł	1-phase: 200 to 240 V, 50/60 Hz 3-phase, 380 to 460 V, 50/60 Hz										
Allowable voltage fluctuation Allowable		-15% to + 10%										
<ul> <li>Allowable</li> <li>fluctuation</li> </ul>		± 5%										
Control method					Sine way	ve PWM (\	//f control)	)				
Speed control range						1: 20						
Speed Control Accuracy						±1%						
Carrier frequency						1kHz to 15	kHz					
Overload capacity				1509	% rated ou	tput curre	nt for one i	minute				
Output frequency resolution						0.01 Hz						
Frequency reference			0 to 10 V,	4 to 20 m/	A, 0 to 20 i	mA or upfr	ont speed	control po	otentiomet	er		
Output frequency resolution Frequency reference signal Frequency accuracy (temperature change) Accel / Decel Time		Digi	tal referen	ice: ± 0.01	% -10 to +	50°C and	Analog re	ference: ±	0.5% 25 ±	±10°C		
Accel / Decel Time					0.1	Sec. to 999	9 Secs					
Protections	Moto	r overload,	Power los	ss ride thro	ough, Fin o	verheat, L	Inder volta	ge, Over v	voltage, St	all prevent	ion, etc.	
Standard functions	spe	ed search	, 9-step m	ulti speed, power los	S-curves, ss (0.5sec	dual acc/c ), slip co	e, frequence lec rates, a mpensatio n, UP/DO	automatic n, DC_inje	restart afte	er fault dete	, ection,	
Digital/Analog I/O ports		1 ana	llog input,	1 analog c	output, 5 di	gital input	s ( three pi	rogramabl	e), 1 digita	l output		
Communication			MEMO	BUS / MOE	DBUS Com	nmunicatio	on (RS-485	6/422 max	. 19.2 kbps	s) (Optiona	I)	
Working ambient					-	-10°C to 50	)°C					
Working ambient temperature Humidity				9	90% RH or	less (non	-condensir	ng)				
Location		Ir	idoors (fre	e from cor	rosive das	es or dust	) and withi	n 1000 m	MSL eleva	tion		

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# Multi Functional Industrial Drive

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V7 is a high performance AC drive for induction motor. Its PWM design provides low motor noise and high starting torque. It provides best speed regulation by two control methods, V/f and open loop vector control which provides high torque at low speed. The V7 is intended for constant torque application, with current overload rating of 150% for 60 sec. The digital operator provides 4-digit LED status display with a built-in analog speed potentiometer and more than 200 programming parameters.

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### Common Applications

- Conveyors
- GrindersCentrifuges
- Pumps
- Fans
- Blowers
- Machine Tools
- Packaging
- Food Processing
- Commercial Laundry

### Features

- Vector control without feedback provides excellent starting torque and performance
- High speed current limit function to eliminate nuisance trip
- Copy keypad function for convenient parameter uploading and downloading
- Digital operator interface for easy and quick configuration
- Speed search function for starting a coasting motor to desired frequency
- Dynamic Braking Transistor is standard for low cost braking with optional resistor

### STANDARD SPECIFICATIONS

	SIANDARD SPECIFICATI											
Vol	tage Class				400 thre	ee phase						
	DEL CIMR-V7AA	40P4	40P7	41P5	42P2	43P0	43P7	45P5	47P5			
Ma	x. applicable KW	0.4	0.75	1.5	2.2	3.0	3.7	5.5	7.5			
Мо	tor output HP*	0.54	1.0	2	3	4.1	5	7.5	10			
S	Inverter rated kVA	1.4	1.6	3.7	4.2	5.5	6.6	11	14			
eristi	Rated output current (A)	1.8	3.4	4.8	5.5	7.2	8.6	14.8	18			
racte	Max. output voltage (V)	380 to 460 V (proportional to input voltage)										
Cha	Rated input volt and frequency	3-phase,380 to 460 V, 50/60Hz										
Control Characteristics	Max. output frequency				400	)Hz						
ပိ	Rated input voltage and frequency			3-ph	ase, 380 to	460 V, 50	/60Hz					
- >	Allowable frequency fluctuation				+/	5%						
Power Supply	Allowable voltage fluctuation				15% to	+10%						
± 0)	Speed control range				1:20 (	V/f), 1:40 (	(OLV)					
	Control Method			V/t	and Open	Loop Con	trol					
	Overload capacity			150% ra	ated output	current fo	r 60 sec					
	Accel / Decel time	0.01 to 6000 sec										
	Carrier frequency	10 kHz										
	Output frequency resolution	0.01 Hz										
	Frequency reference signal	0 to 10 V,4 to 20mA, 0 to 20mA, pulse train input (max 30kHz),upfront speed										
stics		control potentiometer or MEMOBUS comm										
Icteri	Braking torque	Bra	aking transi	stor built-ir	n,braking to	orque in ex	cess of 100	)% achieva	ble			
Output Characteristics	Frequency accuracy (temp. change)			Digital refe	erence: +/-(	0.01% (-10	) to +50*C)					
tput (				Analog ref	erence: +/-	0.5% (25 +	⊦/- to 10*C)	1				
no	Protection	Motor of	overload, p	ower loss ı	ride through	h, fin overh	neat, over/u	ınder voltaç	ge, stall			
		р	revention,	shot ckt, cu	urrent limitir	ng, ground	fault,over/	under torqu	ie			
	Programmable I/O	7	' discrete ir	nput, 3 disc	rete output	t, 1 analog	output, 1a	nalog input	3			
				1 pulse t	rain input 8	k 1 pulse tr	ain output					
	Main control functions	Up to 1	179parame	tersincludi	ngvectorco	ontrol, RS4	85/42219.2	2KBMEMC	BUS			
		comm	s, constants	s copy, PID	control, eve	erysavings	, speed sea	rch16-step	multi-			
			speed, S	G-curves, du	ualacce/de	celerates, c	dcinjection	braking,				
		speed, S-curves, dual acce/decelerates, dcinjection braking, momentary powerloss (0.5 sec), slip commensation (even during regen), UP/DOWN										
ent	Working ambient temperature	-10°C to 50°C										
Envionment	Humidity			90% F	RH or less (	(non-conde	ensing)					
Envi	Location	Indoor (free from corrosive gases or dust) and with in 1000m MSL elevation										
* Page	ased on a standard 4-pole motor for max, applicable motor output											

\* Based on a standard 4-pole motor for max. applicable motor output

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# V1000

**Compact Current Control Vector Drive** Normal & Heavy Duty

**ФСМ**УК



The V1000 drive is incredibly compact, technologically advanced, environmentally responsible package capable of driving induction as well as synchronous motor. With its preset application function and dual rating it can handle wide variety of application ranging from Fan, Pump Compressor, Elevator, Crane Conveyor and many more. V1000 employs dual CPU concept that is 4 times faster than other drives, which improves motor control performance especially in vector control applications. Custom software, network communications, plugin I/O cards, packaging options as among the many choices. V1000 with its highly advanced features stands out in its class and a perfect solutions for most of your applications.

### **Common Applications**

• Pump

• Fan

- HVAC (AHU)
- Conveyor
- Air Compressor
- Crane Hoist
- Crane (Travel)
- Elevator
- Packaging machines
- Extruders
- Centrifuge

### Features

- ➡ 10 years performance life design
- ➡ Normal Duty and Heavy Duty selection depending on the
- application Single drive for both Induction & permanent magnet motors
- Drive customization / PLC functionality
- Dual microprocessor for faster control
- Rotation & Static Auto-tuning
- On-line Auto-tuning
- ➡ 200% starting torque
- Allows side by side mountingreduces panel space
- ➡ High flux braking for faster stopping without use of braking resistors
- Intelligent detachable terminal block
- Stores last 10 faults
- High speed serial communication at 115kbps
- Optional LCD operator

### **STANDARD SPECIFICATIONS**

200	200 V Class (Three-phase/Single-phase)																
N 4	odel	Three-Phase		CIMR-VT2A	0001	0002	0004	0006	8000	0010	0012	0018	0020	0030	0040	0056	0069
IVI	ouei	Single-Phase	*1	CIMR-VTBA	0001	0002	0003	0006		0010	0012		0018				-
		Applicable Mot		Normal Duty	0.2	0.4	0.75	1.1	1.5	2.2	3.0	3.7	5.5	7.5	11.0	15.0	18.5
t	Capa	city*2	kW	Heavy Duty	0.1	0.2	0.4	0.75	1.1	1.5	2.2	3.0	3.7	5.5	7.5	11.0	15.0
Input	Three		Three-	Normal Duty	1.1	1.9	3.9	7.3	8.8	10.8	13.9	18.5	24.0	34.7	50.9	69.4	85.6
_	Rate	d Input	Phase	Heavy Duty	0.7	1.5	2.9	5.8	7.0	7.5	11.0	15.6	18.9	26.0	35.4	51.9	70.8
	Current A Single		Single-	Normal Duty	2.0	3.6	7.3	13.8	-	20.2	24.0	-	-	-	-	-	-
			Phase	Heavy Duty	1.4	2.8	5.5	11.0	-	14.1	20.6	-	35.0	-	-	-	-
	Rated Output			Normal Duty	0.5	0.7	1.3	2.3	3.0	3.7	4.6	6.7	7.5	11.4	15.2	21.3	26.3
	Capacity kVA		kVA	Heavy Duty	0.3	0.6	1.1	1.9	2.6	3.0	4.2	5.3	6.7	9.5	12.6	17.9	22.9
	Rate	d Output Curre	nt Δ	Normal Duty	1.2	1.9	3.5(3.3)	6.0	8.0	9.6	12.0	17.5	19.6	30.0	40.0	56.0	69.0
	Trater	Heavy Dut			0.8	1.6	3.0	5.0	6.9	8.0	11.0	14.0	17.5	250	33.0	47.0	60.0
Output	Over	load Tolerance			Normal Duty Rating: 120% of rated output current for 60 sec Heavy Duty Rating: 150% of rated output current for 60 sec												
	Carri	er Frequency			2 kHz (user-set, up to 15 kHz possible)												
	Max.	Output Voltage	e		Three-Phase Power Supply: Three-Phase 200 to 240 V (relative to input voltage) Single-Phase Power Supply: Three-Phase 200 to 240 V (relative to input voltage)												·
	Max.	Output Freque	ency 400	Hz							400 Hz						
	Rate	d Voltage/Rate	d Freque	ncy									200 to 2 200 to 2				
	Allow	able Voltage F	luctuatio	า						-1	5 to 10	%					
ver	Allow	able Frequenc	y Fluctua	ition							±5%						
Power			Three-	Normal Duty	0.5	0.9	1.8	3.3	4.0	4.9	6.4	8.5	11.0	17.0	24.0	31.0	37.0
	Down	er Supply kVA	Phase	Heavy Duty	0.3	0.7	1.3	2.7	3.2	3.4	5.0	7.1	8.6	11.0	17.0	24.0	31.0
	FOWE	я зарру куд	Single-	Normal Duty	0.5	1.0	1.9	3.6	-	5.3	6.3	-	-	-	-	-	-
			Phase	Heavy Duty	0.4	0.7	1.5	2.9	-	3.7	5.4	-	9.2	-	-	-	-

\*1: Drives with a single-phase power supply input have Three-phase output and cannot be used for single phase motors. \*2: Based on a standard 4-pole motor for max. applicable motor output. Note: Value inside parenthesis is for a single-phase drive

### 400 V Class (Three-phase)

Mo	odel CIMR-VT4A		0001	0002	0004	0005	0007	0009	0011	0018	0023	0031	0038
Ma	ax. Applicable Motor	Normal Duty	0.4	0.75	1.5	2.2	3.0	3.7	5.5	7.5	11.0	15.0	18.5
Ca	apacity <sup>*1</sup> kW	Heavy Duty	0.2	0.4	0.75	1.5	2.2	3.0	3.7	5.5	7.5	11.0	15.0
Input	Rated Input Current A	Normal Duty	1.2	2.1	4.3	5.9	8.1	9.4	14.0	20.0	24.0	38.0	44.0
dul		Heavy Duty	1.2	1.8	3.2	4.4	6.0	8.2	10.4	15.0	20.0	29.0	39.0
	Rated Output	Normal Duty	0.9	1.6	3.1	4.1	5.3	6.7	8.5	13.3	17.5	23.6	29.0
	Capacity kVA	Heavy Duty	0.9	1.4	2.6	3.7	4.2	5.5	7.0	11.3	13.7	18.3	23.6
	Rated Output Current A	Normal Duty	1.2	2.1	4.1	5.4	6.9	8.8	11.1	17.5	23.0	31.0	38.0
Output		Heavy Duty	1.2	1.8	3.4	4.8	5.5	7.2	9.2	14.8	18.0.	24.0	31.0
OU	Overload Tolerance		Normal Duty Rating: 120% of rated output current for 60 sec Heavy Duty Rating: 150% of rated output current for 60 sec										
	Carrier Frequency		2 kHz (user-set, up to 15 kHz possible)										
	Max. Output Voltage		Three-Phase 380 to 480 V (relative to input voltage)										
	Max. Output Frequency						400	Hz (user	-set)				
	Rated Voltage/Rated Fred	quency				Three	e-Phase	380 to 48	30 V 50/6	60 Hz			
Power	Allowable Voltage Fluctua	ition					-	15 to 10	%				
Pov	Allowable Frequency Fluc	tuation						±5%					
	Power Supply kVA	Normal Duty	1.1	1.9	3.9	5.4	7.4	8.6	13.0	18.0	22.0	35.0	40.0
	Power Supply kVA	Heavy Duty	1.1	1.6	2.9	4.0	5.5	7.5	9.5	14.0	18.0	27.0	36.0

\*1: Based on a standard 4-pole motor for max. applicable motor output.



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### **COMMON SPECIFICATION**

### MODEL SELECTION BY MOTOR CAPACITY

	ITEM	SPECIFICATIONS
	Control Method	Open Loop Vector Control (Current Vector), V/f Control, PM Open Loop Vector Control (for SPM and IPM motors)
	Frequency Control Range	0.01 to 400 Hz
	Frequency Accuracy	Digital Input : within ± 0.01% of the max. output frequency (-10° to + 50°C)
	(Temperature Fluctuation)	(Analog Input : within ± 0.1% of the max. output frequency (25°C ±10°C)
	Frequency Setting	Digital Input : 0.01 Hz
	Resolution	Analog Input : 1/1000 of max. frequency
	Output Frequency Resolution	1/2 <sup>20</sup> of maximum output frequency (parameter E1 - 04 setting)
3	Frequency Setting	Main frequency reference : 0 to + 10Vdc (20kΩ) 4 to 20mA (250Ω), 0 to 20mA (250Ω)         Pulse Train Input max. 32 kHz
	Starting Torque	200%/0.5 Hz 50%/6 Hz
5	Speed Control Range	1:100 (Open Loop Vector Control),1:20 to 40 (V/f Control),1:10 (PM Open Loop Vector Control)
$\overline{\mathbf{b}}$	Speed Control Accuracy	± 0.2% in Open Loop Vector Control (25°C ±10°C)
	Speed Response	5 Hz in Open Loop Vector (25°C ± 10°C)
5	Torque Limit	Open Loop Vector Control allows separate settings in four quadrants
	Accel/Decel Time	0.0 to 6000.0 sec (4 selectable combinations)
	Braking Torque	Continuous regen. torque : approx. 20% (approx.125% with dynamic braking resistor option : 10% ED, 10s, internal braking transistor)
	V/f Characteristics	User-selected programs, V/f preset patterns possible
	Main Control Functions	Momentary power loss ride-thru, Speed search, Over torque detection, Torque limit, 17-step speed (max), Accel/Decel time switch, S-Curve accel/decel, 3-wire sequence, Auto-Tuning (Rotational, Stationary tuning for resistance between lines), Cooling fan on/off switch, Slip compensation, Torque compensation, Frequency jump, Upper/Lower limits for frequency reference, DC Injection braking at start and stop, High slip braking, PID control (With sleep function), Energy saving Control, Memobus comm. (RS-485/422 max 115.2 kbps), Fault restart, Application presets, Removable terminal block with parameter backup function
	Protection	Motor overheat protection based on output current, Momentary over-current protection, Overload protection, Over-voltage protection, Undervoltage protection, Momentary power loss ride-thru, Heatsink oveheat, Braking resistance overheat protection, Stall prevention, Ground fault protection
5	Area of Use	Indoors
	Ambient Temperature	$-10^{\circ}$ to $+50^{\circ}$ C
	Humidity	95 RH% or less (no condensation)
-	Storage Temperature	- 20° to + 60° C (short-term temperature during transportation)
	Altitude	Upto 1000 meters
	Shock	10 to less than 20 Hz (9.8m/s <sup>2</sup> ) max., 20 to 50 Hz (5.9 m/s <sup>2</sup> ) max
	Safety Standard	UL 508 C, EN954 - 1Cat. 3, IEC/EN61508 SIL2
	Protection Design	IP20 open-chassis, NEMA1 enclosure

Rotational Auto-Tuning must be performed to achieve the performance described with Open Loop Vector Control.

MODEL		Heavy Duty			Normal Duty	
	kW	Amps	KVA	kW	Amps	KVA
1 PH 220V INPUT						
CIMR-VTBA0001BAA	0.1	0.8	0.3	0.2	1.2	0.5
CIMR-VTBA0002BAA	0.2	1.6	0.6	0.4	1.9	0.6
CIMR-VTBA0003BAA	0.4	3.0	1.1	0.75	3.3	1.3
CIMR-VTBA0006BAA	0.75	5.0	1.9	1.1	6.0	2.3
CIMR-VTBA0010BAA	1.5	8.0	3.0	2.2	9.6	3.7
CIMR-VTBA0012BAA	2.2	11. 0	4.2	3.0	12.0	4.6
CIMR-VTBA0018BAA	3.7	17.5	6.7			
3 PH 220V INPUT						
CIMR-VT2A0001BAA	0.1	0.8	0.3	0.2	1.2	0.5
CIMR-VT2A0002BAA	0.2	1.6	0.6	0.4	1.9	0.7
CIMR-VT2A0004BAA	0.4	3.0	1.1	0.75	3.3	1.3
CIMR-VT2A0006BAA	0.75	5.0	1.9	1.1	6.0	2.3
CIMR-VT2A0008BAA	1.1	6.9	2.6	1.5	8.0	3.0
CIMR-VT2A0010BAA	1.5	8.0	3.0	2.2	9.6	3.7
CIMR-VT2A0012BAA	2.2	11.0	4.2	3.0	12.0	4.6
CIMR-VT2A0018BAA	3.0	14.0	5.3	3.7	17.5	6.7
CIMR-VT2A0020BAA	3.7	17.5	6.7	5.5	19.6	7.5
CIMR-VT2A0030FAA	5.5	25.0	9.5	7.5	30.0	11.4
CIMR-VT2A0040FAA	7.5	33.0	12.6	11.0	40.0	15.2
CIMR-VT2A0056FAA	11.0	47.0	17.9	15.0	56.0	21.3
CIMR-VT2A0069FAA	15.0	60.0	22.9	18.5	69.0	26.3
3PH 415V INPUT						
CIMR-VT4A0001BAA	0.2	1.2	0.9	0.4	1.2	0.9
CIMR-VT4A0002BAA	0.4	1.8	1.4	0.75	2.1	1.6
CIMR-VT4A0004BAA	0.75	3.4	2.6	1.5	4.1	3.1
CIMR-VT4A0005BAA	1.5	4.8	3.7	2.2	5.4	4.1
CIMR-VT4A0007BAA	2.2	5.5	4.2	3.0	6.9	5.3
CIMR-VT4A0009BAA	3.0	7.2	5.5	3.7	8.8	6.7
CIMR-VT4A0011BAA	3.7	9.2	7.0	5.5	11.1	8.5
CIMR-VT4A0018FAA	5.5	14.8	11.3	7.5	17.5	13.3
CIMR-VT4A0023FAA	7.5	18.0	13.7	11.0	23.0	17.5
CIMR-VT4A0031FAA	11.0	24.0	18.3	15.0	31.0	23.6
CIMR-VT4A0038FAA	15.0	31.0	23.6	18.5	38.0	29.0

Normal Duty Application Heavy Duty Application

120% Overload for 1 min on inverter rated output current fans, pumps, variable torque load and application which do not require high overload 150% overload for 1 min on inverter rated output current Constant torque or impact load, like elevator, crane, compressor, Centrifuges and mixers with high viscosity material

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# Indusrial Workhorse Normal And Heavy Duty



The F7 drive is the Industrial Workhorse of adjustable frequency drives. It is intended to handle every conventional drive application found in the typical industrial manufacturing plant from simple variable torque pumping to sophisticated networked material handling. With excellent performance and a wide array of configurations and options, the F7 drive can be the single drive platform for an entire facility. Network communications, plug-in I/O cards, custom software, and power /packaging options are among the many choices. For new installations or retrofits, F7 drive is truly the Industrial Workhorse, perfect for every conventional application and even some unconventional ones.

### **Common Applications**

- Conveyors
- Mixers
- Machine tools
- Cut-to-length
- Centrifugal Pumps
- Centrifuges
- Extruders
- Packaging Machines

### Features

- Constant or variable torque operation for the flexibility to handle all industrial applications
- Rotational and static Auto-tuning for ease of motor configuration
- Closed or open loop vector can deliver outstanding starting torque and performance
- ➡ High speed current limiting to prevent nuisance trips
- High Slip Braking reduces installation cost and eliminates the need for additional braking
- Communication options that support all major industrial networks
- ➡ LCD operator (optional)

### **STANDARD SPECIFICATIONS**

	Model CIMR-F7A						45P51													41320				
	Max. applicable kW Motor output <sup>1</sup> HP	0.4 0.5	0.75 1.0	1.5 2.0	2.2 3.0	3.7 5.0	5.5 7.5	7.5 10.0	11 15	15 20	18.5 25	22 30	30 40	37 50	45 60	55 75	75 100	90 120	110 150	132 180	160 215	185 250	220 300	300 400
	Inverter capacity kVA torque	1.4	1.6	2.8	4.0	5.8	9.8	13	18	24	30	34	46	57	69	85	110	140	160	200	230	280	390	510
	Continuous current *1*2	2.0	2.3	4.0	5.8	8.3	13.6	18.5	26.2	33.8	42.5	49.1	65.4	81.8	99.2	122.1	163.5	196.2	235.4	283.4	331.4	403.3	551.5	735.8
400 V Class	Variable torque current *1	1.9	2.2	3.9	5.5	7.9	13.1	17.7	25.1	32.4	40.7	47.0	62.6	78.3	95.0	116.9	156.6	187.9	225.5	271.4	317.4	386.3	528.3	704.7
ass	OCONSTANT TOTQUE	1.8	2.1	3.7	5.3	7.6	12.5	17.0	24.0	31.0	39.0	45.0	60.0	75.0	91.0	112.0	150.0	180.0	216.0	260.0	304.0	370.0	404.8	540.0
2	පී Max. voltage					3-ph	ase, 3	380/4	00/4	15/44	0/460	0/480	V (P	ropor	tiona	l to in	put v	oltage	e)					
40(	df ff O O						(	CT m	ode :	150	Hz, V	T mo	de : 4	00Hz	z (sele	ectab	le)							
	Rated input voltage							3-ph	nase,	380/4	400/4	15/44	40/46	0/480	)V, 50	)/60H	z							
	Allowable requency										-15	% to	+10%	, D										
	Allowable frequency											±5%	6											
	Harmonic DC Reactor			Option Provided Available																				
	Wave 12- Pulse Prevention input					Not a	vailat	ole											d at 1	2-pui	se inp	out)		
	Control method				[ Op	oen lo	op ve	ector,	V/f, '	V/f wi				PWN select		] , Cl	osed	loop	vecto	or cor	ntrol			
	Starting torque		15	50% a	at 0.5	Hz (C	Open	vecto	or cor	ntrol,	CT m	ode),	120	% at (	0.5 H	z (Op	en lo	op ve	ector	contro	ol, VT	mod	e)	
	Speed control range			1: 100 (Open loop vector control ) 1: 1000 (flux control mode, encoder reqd.) $\pm 0.2\%$ (Open loop vector control at $25^{\circ}C \pm 10^{\circ}C) \pm 0.02$ (flux control)																				
	Speed control accuracy					±	0.2%	o (Op	en lo	op ve	ector	contro	ol at 2	25°C :	± 10°(	C)±0	.02 (	flux c	ontro	l)				
	Speed response									5 Hz	z (Op	ben lo	op v	ector	contr	ol)								
	Torque limit					Ca	n be s	set b	y par	amete	er : 4	steps	s avai	lable	(in oj	pen lo	oop v	ector	cont	rol)				
	Carrier frequency											1kHz	to 1	5kHz										
S	Frequency control range							СТ	mode	e : 0.0	1 to	150 H	lz, V	Г moo	de : 0	.01 to	400	) Hz						
risti	Frequency accurancy				D	igital	refere	ence	: ± 0.	.01 %	, -10	to 40	<sup>0</sup> C, A	Analo	g refe	erence	e:±0	0.1 %	, 25 :	± 10°	0			
Control Characteristics	Frequency setting resolution				D	igital	refere	ence	: ± 0.	.01 H	z, An	alog i	refere	ence :	0.03	Hz/6	0 Hz	(10-b	oit, no	o code	e)			
Cha	Output freq. resolution							<u> </u>					001 H							0001				
itrol	Overioad capacity		C	I moo	de : 1	50%	rated									e whe for 1			20 to	300k	vv inv	erters	5),	
Sol	Frequency setting signal									+10 to	o -10	V, 4 1	to 20	mA, I	Pulse	trair	1							
	Accel / Decel time				0	.01 to	6000	) sec	s. (A	ccel/[	Decel	time	setti	ng inc	leper	ndentl	y, 4 s	steps	avai	lable)				
	Braking torque						A	ppro	x. 20	% (A	ppro>	(. 125	5 % w	hen ι	using	braki	ng re	sisto	r)					
	Main control functions	time Slip	e chai comj	ngeov pensa	ver, S- ation,	∙curve Jump	start, e acce frequ sleep	el/dec iency	cel, 3- v, Free	-wire quenc	sequ sy up	ence, ber/ lo	Auto wer l	-Tunii imit s	ng (dy etting	ynami js, DC	ic. Sta Cinje	atic), ction	DŴE brakii	LL, C ng at	ooling	j fan	ON/C	DFF,
	Digital/analog I/O ports	Thre	ee Ar	nalog	input	(two	progra	amat	ole) <sup>-</sup>	Two A	nalo	g out	out, E	ight [	Digita	l inpu	t ( six	< Prog	gram	able),	three	e digit	al ou	tput
	Pulse I/O							(	One p	oulse	Input	and	Outp	ut ea	ch (3	2 kHz	max	c.)						
	Communication		MEMOBUS / MODBUS communication (RS-485/422 max. 19.2 kbps)																					
	Protective functions		Motor overload protection, Inverter overload, Fuse Protection, Instantaneous overcurrent, Open phase, Undervoltage, Overvoltage, Ground fault, Fin overheat, Stall prevention, etc.																					
	Protective functions		E	Inclos	sed w	all-m	ounte	d typ	e (NE	EMA	1):1	3.5 k\	N or	ess,	Open	chas	sis ty	/pe (I	P00):	: 22	W or	more	9	
Environment	Working ambient temperature											-10°	C to	30 °C										
viron	Humidity									90%	RH	or les	ss (no	on-coi	ndens	sing)								
Ш	Location					Indo	ors (fr	ee fr	om c	orrosi	ve ga	ases	or du	st) an	d wit	hin 10	000 n	n MSI	_ ele\	vation				

Notes : 1. Standard 4-pole motors are used for max. applicable motor output. Choose the inverter whose rated current is within the motor rated current range.

rise in temperature.

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2. Drive Ratings are for ambient temperature of 45°C. For use beyond 45°C, derate by 1.33% per degree

### **OPTIONS, PERIPHERAL DEVICES**

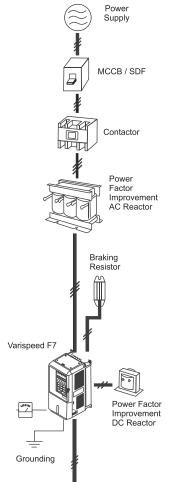
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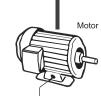
Device	Objective	Details
MCCB or S-D-F	To protect inverter wiring	Always install the MCCB or S-D-F on the power supply side to protect the inverter wiring.
Contactor	To prevent burning of braking reactor	When Braking resistor is attached, install the contactor to prevent the braking resistor from burning. Also insert voltage surge suppressor on the coil.
DC/AC Reactor	To improve inverter power factor	Applied to further improve the power factor of the inverter. The Varispeed F7 incorporates DC Reactor on model of 22kW or more.
Braking Resistor	To stop machine within	Shortens the deceleration time by consuming the regenerative energy of the motor by the resistor.
Braking Unit	the preset time	Used in combination with the braking resistor to reduce the deceleration time of the motor.

# Braking Units and Resistors for V7,F7 & V1000 Drive

	Braking Unit Braking Resistor				stor		
	oplicable output HP	Model CDBR	Qty.	Specifications of Recommended braking resistor	Recommended Qty.		Connectable Min. Resistance
0.4	0.5			70 W 750 Ω	1	230	96
0.75	1.0			70 W 750 Ω	1	130	96
1.5	2.0			260 W 400 Ω	1	125	64
2.2	3.0			260 W 250 Ω	1	135	64
3.7	5.0	Built -	in	390 W 150 Ω	1	135	32
5.5	7.5			520 W 100 Ω	1	135	32
7.5	10.0			780 W 75 Ω	1	130	32
11	15.0			1010 W 50 Ω	1	135	20
15	20			1560 W 40 Ω	1	125	20
18.5	25			4800 W 32 Ω	1	125	19.2
22	29.3	4030	1	4800 W 27.2 Ω	1	125	19.2
30	40	4030	1	6000 W 20 Ω	1	125	19.2
37	50	4045	1	9600 W 16 Ω	1	125	12.8
45	60	4045	1	9600 W 13.6 Ω	1	125	12.8
55	76.3	4030	2	6000 W 20 Ω	2	135	19.2
75	100	4045	2	9600 W 13.6 Ω	2	145	12.8
90	120	4220	1	6000 W 20 Ω	3	100	3.2
110	160	4220	1	6000 W 20 Ω	3	100	3.2
132	180	4220	1	9600 W 13.6 Ω	4	140	3.2
160	213.3	4220	1	9600 W 13.6 Ω	4	140	3.2
185	250	4220	1	9600 W 13.6 Ω	4	120	3.2
220	300	4220	1	9600 W 16 Ω	5	110	3.2
300	400	4220	2	9600 W 3.6 Ω	6	110	3.2

NOTE : 1. Up to 18.5kW only external braking resistors of the recommended rating is required. While using inverters of 22kW and above, CDBR kit and braking resistors of required numbers need to be added.
 2. Ratings are for standard applications. For special applications, contact us.





Connection Scheme

### **RECOMMENDED RATINGS OF REACTORS** FOR ALL DRIVES MODEL

Max. Ap Motor C	oplicable Output	Recommended Input line reactors for 400V class Drive	Recommended Output line reactors (Rated Inductance/	Recommended DC reactor (Rated Inductance/Current)
kW	HP	(Rated Inductance/Current)	Current)	
0.4	0.5	18mH / 1.3A	8.072mH / 2A	28mH / 3.2A
0.75	1.0	8.4mH / 2.5A	4.484mH / 3.6A	28mH / 3.2A
1.5	2.0	4.2mH / 5A	3.329mH / 5A	11mH / 6A
2.2	3.0	3.6mH / 7.5A	2.446mH / 6.6A	11mH / 6A
3.7	5.0	2.2mH / 10A	1.899mH / 8.5A	6.3mH / 12A
5.5	7.5	1.42mH / 15A	1.076mH / 15A	3.6mH / 23A
7.5	10.0	1.06mH / 20A	0.807mH / 20A	3.6mH / 23A
11	15	0.7mH / 30A	0.538mH / 30A	1.9mH / 33A
15	20	0.53mH / 40A	0.448mH / 36A	1.9mH / 33A
18.5	25	0.42mH / 50A	0.359mH / 45A	1.9mH / 33A
22	29.3	0.36mH / 60A	0.294mH / 56A	
30	40	0.26mH / 80A	0.231mH / 70A	
37	50.0	0.24mH / 90A	0.19mH / 80A	
45	60	0.16mH / 120A	0.161mH / 100A	
55	75	0.15mH / 150A	0.115mH / 140A	
75	100	0.11mH / 200A	0.090mH / 180A	DC
90	120	0.11mH / 200A	0.090mH / 180A	reactor inbuilt
110	150	0.09mH / 250A	0.067mH / 240A	mount
132	180	0.09mH / 250A	0.067mH / 240A	
160	215	0.06mH / 330A	0.050mH / 320A	
185	250	0.04mH / 490A	0.045mH / 360A	
220	300	0.04mH / 490A	0.034mH / 630A	
300	400	0.03mH / 660A	0.026mH / 630A	

1. Input line reactor should be a three phase, Iron core air cooled reactor.

2. Output line reactor should be a three phase, Iron core air cooled reactor.

3. DC reactor should be a single phase, Iron core air cooled reactor.

Accessorie	S		
Туре	Cat. Nos.	Function	Applicable For
PG Speed Controller	PG - B2	<ul> <li>Used for V / f control with PG</li> <li>Phase A &amp; B pulse inputs (exclusively for complimentary input)</li> <li>PG frequency range: Approx. 30 kHz max. [Power supply output for PG: +12V, max. Current 30-200 mA]</li> <li>Pulse monitor output: Open collector, +24VDC, Max. Current 30mA</li> </ul>	F7
Card	PG - X2	<ul> <li>Used for V / f control with PG</li> <li>Phase A, B &amp; Z pulse (different pulse) inputs (RS-422 input)</li> <li>PG frequency range: Approx. 300 kHz max [ Power supply output for PG: +5/12VDC, Max. Current 200 mA]</li> <li>Pulse monitor output: RS-422</li> </ul>	F7
	SI - 485/J7	RS23C / 485 Convertor Card - J7	J7
Communications Option Card	SI- P	Profibus - DP Communications I / F Card	F7
	SI - P3/N	Profibus - DP Communications Card	V1000
Digital Operator	JVOP - 160	Digital Operator (LCD) for F7	F7
	JVOP - 180	Digital Operator (LCD)	V1000

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Options & Accessories

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## Dimensions & Weights J7 Drive

## (For 200V 1-PHASE)

**СМ**УК

MODEL CAPACITY IN kW (HP)	REFERENCE FIGURE	DIMEN	DIMENSIONS IN mm						
		W (W1)	H (H1)	D					
0.1 (0.13)	1	68 (56)	128 (118)	70	0.5				
0.2 (0.25)	1	68 (56)	128 (118)	70	0.5				
0.4 (0.5)	1	68 (56)	128 (118)	112	0.9				
0.75 (1)	2	108 (96)	128 (118)	129	1.5				
1.5 (2)	2	108 (96)	128 (118)	154	1.5				

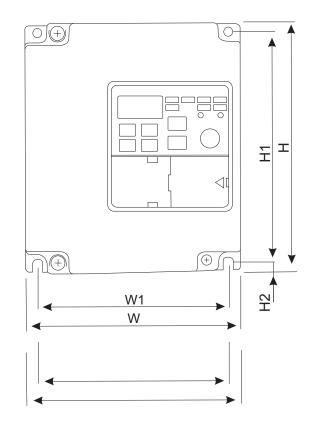
## (For 400V 3-PHASE)

MODEL CAPACITY IN kW (HP)	REFERENCE FIGURE	DIMENS	SIONS IN r	nm	MASS IN KG
		W (W1)	H (H1)	D	
0.2 (0.25)	2	108 (96)	128 (118)	81	1
0.4 (0.5)	2	108 (96)	128 (118)	99	1.1
0.75 (1)	2	108 (96)	128 (118)	129	1.5
1.5 (2)	2	108 (96)	128 (118)	154	1.5
2.2 (3)	2	108 (96)	128 (118)	154	1.5
3.7 (5)	2	140 (128)	128 (118)	161	2.1

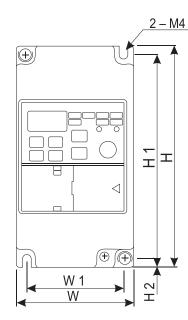
## Dimensions & Weights V7 Drive

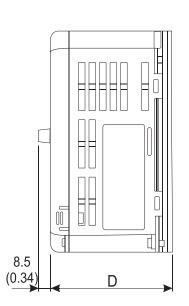
## Mechanical Dimension And Weight For 400V-3 Phase

Model Capacity	Reference	Dim	ensions in mm	I	Mass
In KW (HP)	Figure	W (W1)	H (H1)	D	In KG
0.2(0.25)	3	108(96)	128(118)	92	1
0.4(0.5)	3	108(96)	128(118)	110	1.1
0.75(1)	3	108(96)	128(118)	140	1.5
1.5(2)	3	108(96)	128(118)	156	1.5
2.2(3)	3	108(96)	128(118)	156	1.5
3.7(5)	3	140(128)	128(118)	143	2.1
5.5(7.5)	3	180(164)	260(244)	170	4.8
7.5(10)	3	180(164)	260(244)	170	4.8



All mounting screws are M4 Dimensions in mm

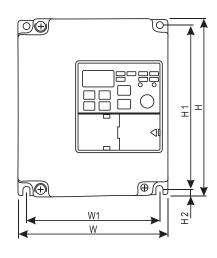




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Figure1



Dimensions in mm

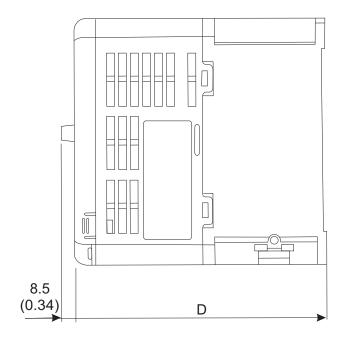


8.5 (0.34)



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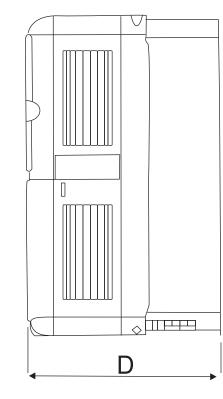
### Figure3

## Dimensions & Weights F7 Drive

**СМ**УК

Voltage	Motor	Open Cha	assis Type	(IP00) mm	Mass	Enclosed	Type [NEM	A1 (Type1)] mm	Mass	DC								
Output	kW	W	Н	D	Kg	W	H	D	Kg	Reactor								
	0.4																	
	0.75	140	280	160	3	140	280	160	3									
	1.5																	
	2.2									<b>•</b> "								
	3.7	140	280	180	4	140	280	180	4	Option								
	5.5									-								
	7.5	200	300	200	6	200	300	200	6									
	11																	
	15	240	350	210	10	240	350	210	10									
	18.5																	
400 V	<u>22</u> 30	275	450	260	21	279	535	260	24									
Class	30									-								
	45	325	550	285	285	285	285	285	285	285	285	285	36	329	635	285	40	
	55	020		200	00	020	715	200										
	75				88				96									
	90	450	725	350	89	455	1100	350	97	Built-in								
	110	= = = =			102	505	10.15	000	122									
	132	500	850	360	120	505	1245	360	130									
	160	575	916	378	160	579	1324	378	170									
	185	740	1005	440	260													
	220	710	1305	413	280		Not	available										
	300	916	1475	413	405													

# ,4-D W





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Dimensions & Weights V1000 Drive

Enclosures MODEL Voltage Figure CIMR- VT Class W D BA0001 128 76 68 1 BA0002 68 128 76 200 V BA0003 1 68 128 118 137.5 Class BA0006 108 128 Single-BA0010 1 108 128 154 BA0012 140 128 163 phase BA0018 170 128 180 4A0001 108 128 81 1 4A0002 108 128 99 4A0004 108 128 137.5 400 V 4A0005 108 128 154 Class 4A0007 108 128 154 1 Three-4A0009 108 128 154 phase 4A0011 140 128 143 4A0018\* 140 254 140 4A0023\* 140 254 140 2

180

180

290

290

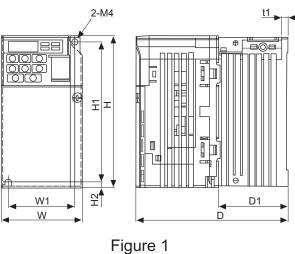
143

163

Open-Chassis (lp20)

4A0031\*

4A0038\*



Dimensions in mm

**L&T SWITCHGEAR** SAFE & SUF

Dimensions (mm) Weight					Weight	Cooling	
W1	H1	H2	D1	t1	Mtg. Holes	kg	Cooling
56	118	5	6.5	3	M4	0.6	
56	118	5	6.5	3	M4	0.6	Self-
56	118	5	38.5	5	M4	1.0	cooled
96	118	5	58	5	M4?	1.7	
96	118	5	58	5	M4	1.8	<b>F</b>
128	118	5	65	5	M4	2.4	Fan cooled
158	118	5	65	5	M4	3.0	cooleu
96	118	5	10	5	M4	1.0	Salf
96	118	5	28	5	M4	1.2	Self- cooled
96	118	5	58	5	M4	1.7	000104
96	118	5	58	5	M4	1.7	
96	118	5	58	5	M4	1.7	Fan
96	118	5	58	5	M4	1.7	cooled
128	118	5	65	5	M4	2.4	
122	248	13	55	5	M5	3.8	
122	248	13	55	5	M5	3.8	Fan
160	284	13	55	5	M5	5.2	cooled
160	284	13	75	5	M5	5.5	

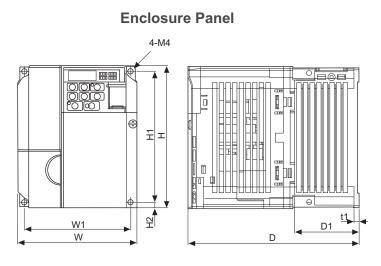


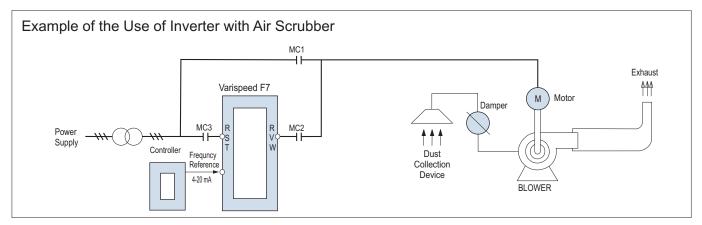
Figure 2

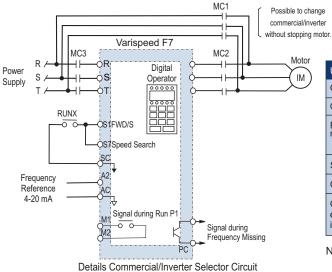
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### **Application Examples**

**СМ**УК

### Fans and Blowers (contributes to Energy-Saving and Improved Performance)





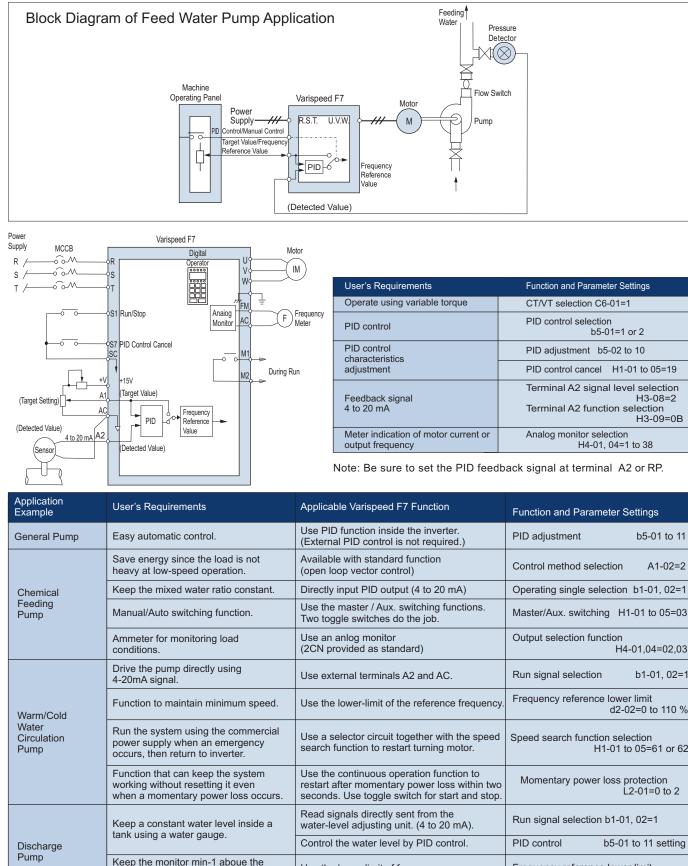
User's Requirements	Function and Parameter Settings
Operate using variable torque	CT/VT selection C6-01=1
Operate using control circuit terminal	Reference selection b1-01, 02=1
Frequency reference range 4 to 20mA	Terminal A2 single level selection H3-08=2 Terminal A2 function selection H3-09=2 Terminal A1 and A2 switching H3-13=1
Speed search function	Multi-function input H1-05=61 or 62
Coast to stop	Stopping method selection b1-03=1
Continue operation even if failure occurs in frequency reference	Operation when frequency reference is missing L4-05=1 Reference loss signalH2-02=0 C

Note: In this case, be sure to coast to a stop when selecting inverter stopping method.

Application Example	User's Requirements	Applicable Varispeed F7 Function	Function and Parameter Settings
	Switch commercial power supply and inverter drive without stopping the motor. To start a coasting motor to desired frequency without stopping the motor.	Use the speed search operation.	Multi-function input H1-01 to 05=61 or 62
	Save energy since the load is not heavy at low-speed operation.	Apply the variable load V/f.	V/f selection E1-03=05 or 07
Dust	Avoid overload tripping.	Apply the torque limit function.	Torque limit L7-01=0-300 %
Collection System Blower,	Continue operation even when momentary power loss not longer than 2 second occur.	Select the momentary power loss reset and restart mode.	Momentary power loss protection L2-01=0 to 2
Fan for Boilers Fan for Cooling	Continue operation in case of loss of reference signal.	Select the automatic continues operation mode when frequency reference is missing.	Operating single selection L4-05=0 to 1 Frequency reference is missing H2-01 to 03=0 C
Towers	Monitor output power.	Turn the monitor to the output power indication.	Monitor display U1-08
	R/ min lower limit for lubricating the gear bearing.	Use the frequency reference lower limit.	Frequency reference lower limit d2-02=0 to 110 %
	Avoid mechanical resonance.	Use the preset frequency band prohibition function (frequency jump	Jump frequency d3-01 to 03=0 to 400 Hz
		control). Up to 3 frequencies prohibited.	Jump frequency width d3-04=0 to 20.0 Hz
	To prevent machine stoppage caused by inverter tripping.	Use the fault retry function.	Fault retry count L5-01=0 to 10 times

\*Above mentioned scheme and parameter settings correspond to F7 drives, however the same application can be addressed using other models.

### Pump (Ease of Automatic Control Ensures Performance Consistency)



\*Above mentioned scheme and parameter settings correspond to F7 drives, however the same application can be addressed using other models.

Use th

refere

minimum because if the min-1 is too low

water flows in the reverse direction.

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User's Requirements	Function and Parameter Settings
Operate using variable torque	CT/VT selection C6-01=1
PID control	PID control selection b5-01=1 or 2
PID control characteristics	PID adjustment b5-02 to 10
adjustment	PID control cancel H1-01 to 05=19
Feedback signal 4 to 20 mA	Terminal A2 signal level selection H3-08=2 Terminal A2 function selection H3-09=0B
Meter indication of motor current or output frequency	Analog monitor selection H4-01, 04=1 to 38

cable Varispeed F7 Function	Function and Parameter Settings
PID function inside the inverter. rnal PID control is not required.)	PID adjustment b5-01 to 11
able with standard function loop vector control)	Control method selection A1-02=2
tly input PID output (4 to 20 mA)	Operating single selection b1-01, 02=1
he master / Aux. switching functions. oggle switches do the job.	Master/Aux. switching H1-01 to 05=03
an anlog monitor provided as standard)	Output selection function H4-01,04=02,03
external terminals A2 and AC.	Run signal selection b1-01, 02=1
he lower-limit of the reference frequency.	Frequency reference lower limit d2-02=0 to 110 %
a selector circuit together with the speed h function to restart turning motor.	Speed search function selection H1-01 to 05=61 or 62
he continuous operation function to t after momentary power loss within two nds. Use toggle switch for start and stop.	Momentary power loss protection L2-01=0 to 2
signals directly sent from the -level adjusting unit. (4 to 20 mA).	Run signal selection b1-01, 02=1
ol the water level by PID control.	PID control b5-01 to 11 setting
he lower-limit of frequency ence.	Frequency reference lower limit d2-02=0 to 110 %

### **General Information**

**СМ**УК

- An AC or DC reactor should be installed in the following conditions:
  - •to suppress harmonic currents.
  - •to suppress peak currents when power factor correction capacitors in the power supply network are switched.
  - •when the drive is connected to the same power supply system with thyristor converters like DC drives.
- When running a specialized motor or more than one motor in parallel from a single drive, the capacity of the drive should be larger than 1.1 times of the total motor rated current.
- Terminals B1, B2, F, +1, +2, are provided for connecting optional features for the drive. Do not connect other equipment designed by other manufacturers.
- Acceleration / deceleration times are affected by how much torque the motor generates the load torque.
- Never connect the power supply lines to output terminals U/T1, V/T2 or W/T3. Doing so will destroy the drive. Be sure to perform a final check of all sequence wiring and other connections before turning the power on. Make sure there are no short circuits on the control terminals (+V, AC, etc.), as this could damage the drive.
- As a general principle, the user should avoid opening and closing the magnetic contactor between the motor and the drive during run. Doing so can cause high peak currents and over current faults. If magnetic contactors are used to bypass the drive by connecting the motor to the power supply directly, make sure to close the bypass not before the drive is stopped and fully disconnected from the motor. If the motor start running even while coasting, select the speed search functions. Set up delayed release when using a magnetic contactor to handle momentary power loss.
- In case of submersible motor, since rated current is greater than a standard motor, select the drive capacity accordingly. Be sure to use a large enough motor cable to avoid decreasing the maximum torque level on account of voltage drop caused by a long motor cable.
- Variable speed drives are not designed for operating single phase motor. Using a capacitor to start the motor causes excessive current to flow into the capacitor, potentially causing damage. A slitphase start or a repulsion start can end up burning out the starting coils because the internal centrifugal switch is not activated. The drive can only be used with three phase motors.

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	L&T SWITCHGEAR
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